

L Number	Hits	Search Text	DB	Time stamp
-	4102	vehicle same sensor same object	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:13
-	1053	(vehicle same sensor same object) and path	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:17
-	193	((vehicle same sensor same object) and path) and detect\$ and analyz\$	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:22
-	64	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:24
-	57	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:27
-	49	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:29
-	39	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (account or story or list)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:30
-	36	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:33
-	30	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)) and motion	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:35
-	16	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)) and motion) and instantaneous\$	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:36
-	16	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)) and motion) and instantaneous\$) and measure\$	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:38
-	14	((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)) and motion) and instantaneous\$) and measure\$) and (error or mistake)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:39

-	13	(((((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)) and motion) and instantaneous\$) and measure\$) and (error or mistake)) and model	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:40
-	12	(((((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)) and motion) and instantaneous\$) and measure\$) and (error or mistake)) and model) and correct\$	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:42
-	10	(((((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)) and motion) and instantaneous\$) and measure\$) and (error or mistake)) and model) and correct\$) and deviation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:44
-	10	(((((vehicle same sensor same object) and path) and detect\$ and analyz\$) and calibrat\$) and data) and (stationary or fixed)) and (account or story or list)) and motion) and instantaneous\$) and measure\$) and (error or mistake)) and model) and correct\$) and deviation) and minimiz\$	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 17:59
-	0	(vehicle with path) same (calibea\$ with sensor) same object	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:15
-	0	vehicle same (calibea\$ with sensor) same object	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:16
-	2	(vehicle with path) same (calibra\$ with sensor) same object	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:17
-	36	vehicle same (calibra\$ with sensor) same object	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:19
-	8	(vehicle same (calibra\$ with sensor) same object) and detect\$ and analyz\$	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 21:54
-	7	((vehicle same (calibra\$ with sensor) same object) and detect\$ and analyz\$) and data) and ((stationary or fixed) same motion)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:36
-	0	((vehicle same (calibra\$ with sensor) same object) and detect\$ and analyz\$) and data) and ((stationary or fixed) same motion)) and (deviation same error)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:40
-	1	((vehicle same (calibra\$ with sensor) same object) and (deviation same error)) and (data with model)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:53

-	3	(vehicle same (calibra\$ with sensor) same object) and (deviation same error)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:52
-	8	((vehicle same (calibra\$ with sensor) same object) and detect\$ and analyz\$) and data	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/10 18:54
-	79423	vehicle same sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:17
-	19060	(vehicle same sensor) and data	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:14
-	1196	vehicle same calibrat\$ same sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:19
-	542	(vehicle same calibrat\$ same sensor) and object	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:19
-	357	((vehicle same calibrat\$ same sensor) and object) and data	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:21
-	87	((vehicle same calibrat\$ same sensor) and object) and data) and stationary	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:23
-	38	((vehicle same calibrat\$ same sensor) and object) and data) and stationary) and motion	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:23
-	26	((vehicle same calibrat\$ same sensor) and object) and data) and stationary) and motion) and error	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:24
-	4	((vehicle same calibrat\$ same sensor) and object) and data) and stationary) and motion) and error) and deviation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/15 15:26
-	17971	calibrat\$ with (sensor or sensors)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 21:56
-	18	(calibrat\$ with (sensor or sensors)) and (object with path with vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 21:59
-	217	(calibrat\$ with (sensor or sensors)) and (path with vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:00

-	264	(calibrat\$ with (sensor or sensors)) and (motion with vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:19
-	17	((calibrat\$ with (sensor or sensors)) and (motion with vehicle)) and (object with stationary)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:03
-	13	((calibrat\$ with (sensor or sensors)) and (motion with vehicle)) and (object with stationary)) and (sensors or sensing)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:05
-	0	((calibrat\$ with (sensor or sensors)) and (motion with vehicle)) and (object with stationary)) and (sensors or sensing)) and (model with object)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:05
-	6	((calibrat\$ with (sensor or sensors)) and (motion with vehicle)) and (object with stationary)) and (sensors or sensing)) and (model)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:06
-	6	((calibrat\$ with (sensor or sensors)) and (motion with vehicle)) and (object with stationary)) and (sensors or sensing)) and (error)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:06
-	7	((calibrat\$ with (sensor or sensors)) and (motion with vehicle)) and (object with stationary)) and (sensors or sensing)) and (error or errors)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:06
-	2398	(calibrat\$ with (sensor or sensors)) and (vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:20
-	1312	((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:21
-	759	((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:23
-	383	((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (path)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:24
-	381	((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:31
-	287	((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:32
-	236	((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:34

-	203	(((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:37
-	54	(((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:38
-	40	(((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:39
-	30	(((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)) and (velocity)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:44
-	0	"258" and ((rotatinal or pitching) same motion)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:45
-	0	(((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)) and (vector or vectors)) and ((rotatinal or pitching) same motion)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:45
-	0	(((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)) and (vector or vectors)) and ((rotatinal or pitching) with motion)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:46

-	0	((((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)) and (vector or vectors)) and ((rotatinal or pitching))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:46
-	7	((((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)) and (vector or vectors)) and (image same recording)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:51
-	0	((((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)) and (vector or vectors)) and (camera)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:52
-	3	((((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)) and (vector or vectors)) and (calibrating)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:52
-	32	((((((((calibrat\$ with (sensor or sensors)) and (vehicle)) and (object)) and (error\$ or deviation)) and (learn or learning or train or training or model)) and (motion or movement)) and (store or stored or storing)) and (correct or correcting or corrected or minimizing or minimize or minimized)) and (probability or confidence)) and (stationary or quasi-stationary)) and (vector or vectors)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/17 22:57
-	1269	(calibrat\$5 with sensor\$5) with character\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 13:23
-	24	(calibrat\$5 with sensor\$5) with (character\$6 with deviat\$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 13:31
-	4	702/\$.ccls.and(calibrat\$5 with sensor\$5) with (character\$6 with deviat\$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 13:25

-	18061	(calibrat\$5 with sensor\$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 13:33
-	29995	character\$6 adj1 data	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 14:07
-	176	((calibrat\$5 with sensor\$5)) and (character\$6 adj1 data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 14:07
-	22144	deviat\$4 with error\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 13:35
-	1354	deviat\$4 adj1 error\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 13:48
-	20	702/\$.ccls.and ((calibrat\$5 with sensor\$5)) and (character\$6 adj1 data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 13:35
-	74	sens\$4 with deviat\$4 adj1 error\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 13:49
-	12	sens\$4 with (deviat\$4 adj1 error\$3)with correct\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 14:02
-	182237	character\$6 with data	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 14:09
-	26	((calibrat\$5 with sensor\$5)) same (character\$6 adj1 data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 14:51
-	176	((calibrat\$5 with sensor\$5)) and (character\$6 adj1 data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 15:28
-	1		USPAT	2002/04/18 15:18
-	1		USPAT	2002/04/18 15:20
-	1		USPAT	2002/04/18 15:21
-	113	((calibrat\$5 with sensor\$5)) and (character\$6 adj1 data)) and object	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 15:30
-	17	((calibrat\$5 with sensor\$5)) and (character\$6 adj1 data)) and object) and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/04/18 15:31